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# Exoskeletons for DOE-EM and other Hazardous Operations

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# US DOE Office of Environmental Management

- **Responsible for clean-up of national nuclear legacy**
  - 15+ sites across the country
  - Thousands of workers performing physically challenging work
  - Work includes waste processing, storage, environmental remediation, and decommissioning activities
  - Decades of work remain
- **Work DOE-EM Sites Present Unique Safety Challenges**
  - Extensive PPE generally required to protect from external hazards
  - Musculoskeletal injuries remain common
  - PPE (including SCBA) can increase ergonomic strains
  - Much of the work is complex and non-repetitive
  - Workforce is rapidly aging





# DOE-EM and Other Nuclear Cleanup Worker Challenges

- **Nuclear Cleanup Workforce Safety Challenges**

- Environments and tasks are complex, making automation or teleoperation difficult or impossible
- Environments can be very hot/cold
- Body temp and heartrate are often monitored prevent overexertion

- **Examples of challenging tasks**

- Maintenance, construction, demolition
- Material movement of large/awkward sizes
- Manual excavation
- Lead blanket (45-90 lbs) movement
- Glove box / hot cell operations
- Warehouse operations
- Custodial services
- Etc.







# DOE-EM Wearable Robotics Program Overview

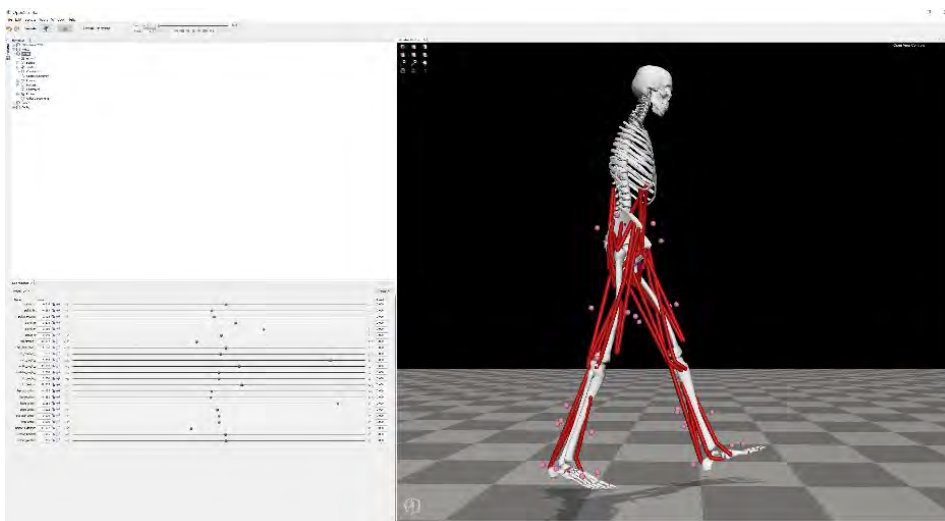
- Funded by DOE-EM Office of Technology Development and led by Sandia
- Team members from DOE Labs, academia, and industry
- Working with EM sites to evaluate and deploy commercially-available exoskeletons
- Biomechanical analysis of commercial and experimental systems
- Developing novel systems for potential future challenges





# DOE-EM Exoskeleton Testbed

- Established at Sandia to evaluate exos specifically for DOE tasks
- Many commercial devices available for testing
- Test equipment includes:
  - Motion capture
  - Instrumented treadmill
  - Metabolic measurement
  - EMG
  - Surveys
- EM site tasks can be emulated with relevant PPE to assess device compatibility and effectiveness







# EM Site Wearables Pilot Programs

- **Sandia National Labs is working with Washington River Protection Solutions to evaluate the potential impact of wearable devices at the Hanford site**
  - Provides objective evaluation of commercial technologies
  - Also working with SRS, WIPP, OREM, and other EM sites
- **Pilot program activities include:**
  - On-site technology demonstrations
  - Emulation of site tasks in Sandia testbed
  - Mock-up work with wearable devices at sites
  - Surveys to assess worker perception of the technology
  - Working with site safety teams to develop approval procedures for on-site use of wearables







# Wearable devices: Shoulder and Arm Support



**Ottobock ShoulderX**

**Assistance Type:** Passive  
**Advertised Use Cases:**  
Overhead tasks



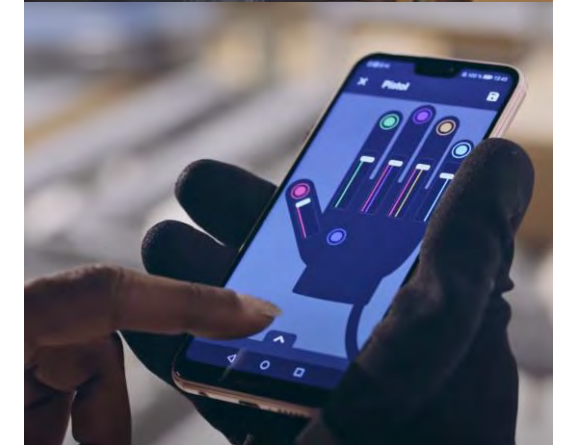
**Ekso Evo**

**Assistance Type:** Passive (Gas Springs)  
**Advertised Use Cases:**  
Overhead tasks



**ErgoSante Hapo MS**

**Assistance Type:** Passive (Springs)  
**Advertised Use Cases:** Work requiring arms at height of 0 to 135 degrees



**BioServo's Ironhand**

**Assistance Type:** Active (DC Motor Cable System)  
**Advertised Use Cases:** All activities requiring gripping



# Wearable devices: Back Support



**Laevo V2.5**

**Assistance Type:**

Passive (Gas Springs)

**Advertised Use Cases:**

Bending, leaning, carrying



**ErgoSante Hapo**

**Assistance Type:**

Passive (Springs)

**Advertised Use Cases:**

Bending, lifting



**Herowear APEX**

**Assistance Type:** Passive (Elastic bands)

**Advertised Use Cases:**

Lifting, bending, crouching, carrying



**SuitX BackX**

**Assistance Type:**

Passive (Torsional Springs)

**Advertised Use Cases:**

Lifting, carrying, bending





## Wearable devices: Lower Body



**DEPHY Exoboot**

**Assistance Type:** Active  
(DC Motors)  
**Advertised Use Cases:**  
Walking/Hiking



**Lockheed Martin ONYX**

**Assistance Type:** Active (DC Motors)  
**Advertised Use Cases:** Walking/Hiking,  
carrying heavy load



**Noonee Chairless Chair**

**Assistance Type:** Passive  
**Advertised Use Cases:**  
“Activities that can be  
performed in sitting position”



## Next Steps

- Manual shoveling study being prepared at Exo Testbed
- Hanford interactions continue, including working with safety teams to develop approval plans for device deployment
- SRNL and LANL are working with other sites on similar activities
- FIU and IHMC continue development and testing of novel systems







# Hanford Wearables Pilot Program Activities

- A few task have been initially evaluated with workers at the site, including
  - Sampling in glove bags
  - PPE laundry
  - Manual excavation
- Workers complete surveys to assess perception of the devices



Exoskeleton Used: ☐ HeroWear ☐ BackX ☐ ShoulderX ☒ Ngonee ID#: \_\_\_\_\_ Date: 10-11-22

Tasks Performed and Duration Used (hours):

	(0-1)	(2-4)	(4-6)	6+
Crank Operator	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
Bag Operator	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
Seal Out	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
Lifting	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
Other 1: _____	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
Other 2: _____	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>

How comfortable was the device throughout the day?  
☐ 1 ☐ ☐ ☐ ☐ ☐ ☒ ☐ 10

How helpful or hindering was the device throughout the day?  
Hindering ☐ ☐ ☐ ☐ ☐ ☒ ☐ Helpful

How easy was it to don, wear, and doff the device with PPE?  
Easy ☐ ☒ Neither ☐ ☐ Difficult

The device benefited: It was nice to step back and have a ~~rest~~ little sit down.

What was difficult to do with the device? No

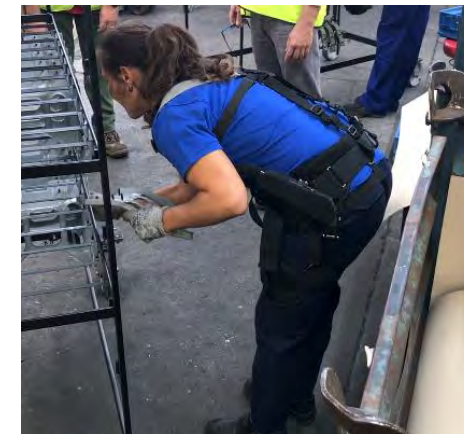
Other comments: The straps on the chest harness had a lot of rubbing under the arms.





## Pilot program survey results to date

- Four devices tested in various tasks
  - Noonee Chairless Chair
  - Back-X
  - Shoulder-X
  - Herowear Apex
- Workers complete surveys to assess perception of the devices



Number of instances*	Device	Comfort (1-10)	Hinder/Helpfulness (-4 to 4)	don/wear/doff ease** (-2 to 2)
7	Noonee	6.8	1.6	1.2
9	BackX	7.3	2.0	2.0
8	ShoulderX	7.7	2.3	0.4
14	HeroWear	8.3	1.9	2.0

Note:

\*refers to the total number of survey responses, regardless of the number of questions answered.

\*\*don/wear/doff numbers only available from Jan2023 visit

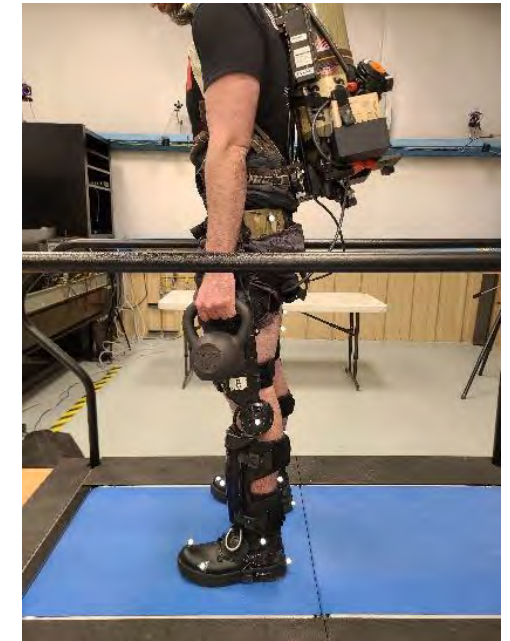






## DOE-EM Testbed Activities

- Completed a study for tank farm workers wearing SCBA
- Three lower-body devices tested over several tasks in simulated shift
  - DEPHY Exoboot
  - Lockheed Martin ONYX
  - Noonee Chairless Chair
- Metabolics, kinematics, and subjective feedback recorded
- Survey results for two participants:



	Exoboot	Onyx	Noonee	No Exo
Comfort	1	4	2	3
Overall Helpfulness	1	4	2	3
Walking	1	2	4	3
Hand Dexterity Test	3	4	1	2
Weighted Walking	1	2	4	3
Weightlifting	2	4	3	1
Incline	1	3	4	2
Rest	2	4	1	3

	Exoboot	Onyx	Noonee	No Exo
Comfort	2	3	4	1
Overall Helpfulness	2	1	4	3
Walking	3	2	4	1
Hand Dexterity Test	2	3	4	1
Weighted Walking	3	2	4	1
Weightlifting	3	1	4	2
Incline	3	1	4	2
Rest	3	1	4	2